

Exam Code: E20-510 Exam Name: business continuity specialist exam

Vendor: EMC

Version: DEMO

# Part: A

1: Which TimeFinder command would restore a set of BCV devices back to their standard pairs?

A.symdev restore full namedg all

B.symmir namedg restore ull oprompt

C.symrdf -g namedg -full oprompt restore all

D.symmir namedg restore BCV dev 0b3 DEV002 -noprompt

# Correct Answers: B

2: Which three [3] statements describe the EMC PowerPath Volume Manager (PowerVolume) 4.x Integration with Business Continuity Solutions Enabler operation?

A.Manually creates device groups from Volume Groups

B.Automatically creates device groups from Volume Groups

C.Recognizes and enables use of space in same target size after split

D.Recognizes and enables use of space in larger sized target after split

E.Gives user ability to import BCV copy on same host or different host as result of a split

# Correct Answers: B D E

## 3: Click the Exhibit button.

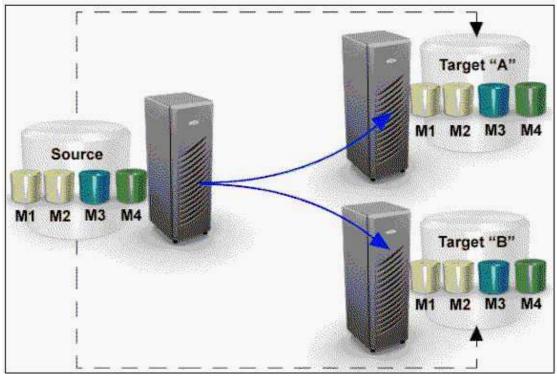
Look at the output of "powermt display dev=128a" command. What is the PowerPath Load Balancing policy and device priority associated with LV 128?

Pseudo name=emcpower128a Symmetrix frame ID=000184500642; volume ID=146 state=alive; policy=SymmOpt; priority=0; queued-IOs=0										
Host Devices - ### HW-path	device	- Symm - director	Path mode state	20703782383						
4 sbus@a/fca@1/sd@1	c4t1d8s0	FA 4a	active open	0 0						
5 sbus@a/fca@2/sd@1	c5t1d8s0	FA 4b	active open	0 1						

A.rr policy and 0 priority B.bf policy and 0 priority C.so policy and 0 priority D.so policy and 146 priority **Correct Answers: C** 

4: Click the Exhibit button.

An SRDF source R1 volume is concurrently paired with an SRDF R2 volume "Target A" and another R2 volume "Target B". Which combination of SRDF modes between the two pairs is NOT allowed?



A.One pair in Synchronous mode; the other pair in Synchronous mode

B.One pair in Synchronous mode; the other pair in Semi-Synchronous mode

C.One pair in Synchronous mode; the other pair in Synchronous mode with a secondary mode of Adaptive Copy Disk

D.One pair in Synchronous mode; the other pair in Synchronous mode with a secondary mode of Adaptive Copy Write Pending

## **Correct Answers: B**

5: What are two [2] types of agents within the ControlCenter infrastructure?

A.Store Agent

B.Server Agent

C.Master Agent

D.Symmetrix Agent

E.Repository Agent

## Correct Answers: C D

6: What are the three [3] ANSI Standard Fibre Channel Network Topologies?
A.iSCSI
B.Point to Point
C.Arbitrated Loop
D.Gigabit Ethernet
E.Switched Fabric
Correct Answers: B C E

7: Which two [2] tools are used to manage and configure Connectrix M-Series switches? A.Telnet

B.DS-M ConnectC.Hyper TerminalD.Connectrix ManagerE.Embedded Web Server (EWS)Correct Answers: D E

8: Click the Exhibit button.

A part of the output from the symdev show 097 command is shown. What type of device is 097?

# syndev show 097		*									
Front Director Paths (1)	:										
			DIR	ECTOR	PORT			L	UN		
PdevName		Туре	Туре	Num	Sts	VBUS	TID	SYMM	Host		
/dev/rhdisk27 }		N/A	FA	13A:0	RW	000	00	050	000		
Mirror Set Type	:	[R1 Remote,Data,Data,N/A]									
Mirror Set DA Status	2	[RW, RW, RW, N/A]									
Mirror Set Inv. Tracks	:	[0,0,0,0]									

A.A locally mirrored BCV

B.A locally mirrored SRDF R1 volumeC.A locally mirrored SRDF R2 volumeD.A parity RAID protected SRDF R2 volumeCorrect Answers: C

9: What is the maximum number of BCVs that can be concurrently established with a locally protected standard Symmetrix device?

A.1 B.2

Б.2 С.4

C.4

D.0 E.8

Correct Answers: B

10: What is the purpose of the symrdf update command?

A.A symrdf update command will reinitialize all the SRDF device groups

B.When in a Failover state, the update function will reset the /var/symapi/db/symapi\_db.bin file C.In an SRDF Fallback state, the update command will restore the R2 Volumes back to the R1 Volumes

D.In an SRDF Failover state, update will begin synchronization prior to resuming operations on the source volumes

# Correct Answers: D

11: In an SRDF/A configuration, why is it recommended to have BCVs attached to the R2 devices

at the remote site?

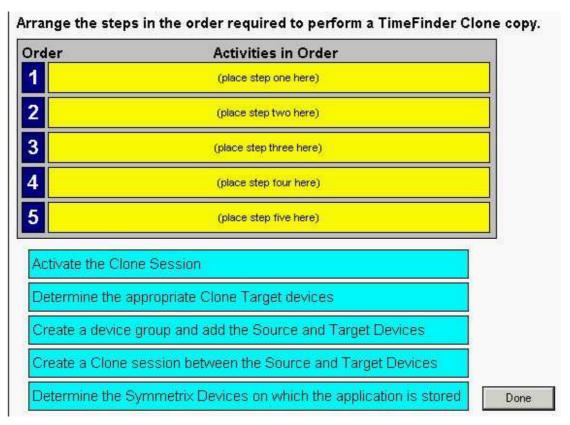
A.To mirror R2 devices for backup purpose in a disaster recovery scenarioB.To preserve a consistent copy of data at the remote site before a split operationC.To preserve extra tracks that would not fit into the cache of R2's COVD devicesD.To preserve a consistent copy of data at the remote site before a resynchronization operationCorrect Answers: D

12: Which two [2] device types must be configured on a Symmetrix Array for TimeFinder Snap operations?
A.BCV Devices
B.Save Devices
C.Virtual Devices
D.SRDF Devices
E.Parity RAID Devices
Correct Answers: B C

13: Which three [3] statements describe Symmetrix GigE Channel Directors?
A.Compression can be turned off
B.Outboard compression hardware is always required
C.Prior to DMX, the GigE Director did not perform data compression
D.The GigE SRDF data flow uses two round trips per transfer operation
E.The GigE Director network bandwidth usage can be throttled downward
Correct Answers: A C E

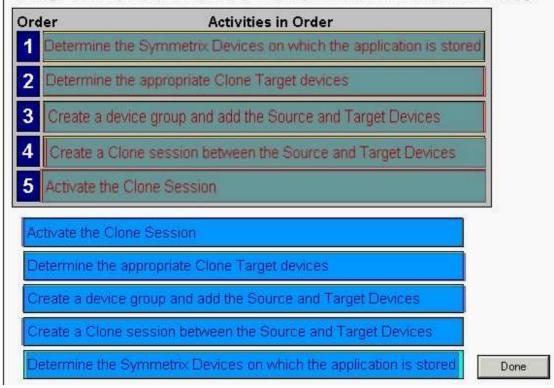
14: Click the Task button.

Arrange the steps in the order required to perform a TimeFinder Clone copy.



## **Correct Answers:**

## Arrange the steps in the order required to perform a TimeFinder Clone copy.



15: Which SYMCLI command would be used to perform a failover, a dynamic SRDF swap and an establish of the swapped SRDF pair? This is also referred to as a Fast Swap Establish.A.symrdf mydg swap -establish

B.symrdf mydg failover stablish
C.symrdf mydg failover -swap -establish
D.symrdf mydg swap ailover -establish
Correct Answers: B