



**Exam Code:** HP0-918

**Exam Name:** HP Storage Data Protector 6.0

Fundamentals for Windows

**Vendor:** HP

**Version:** DEMO

## Part: A

1: How can you collect debug files from distributed Data Protector clients in the environment?

- A. Use the omnidlc command.
- B. Use the devbra collector.
- C. Use the omnitrig process.
- D. Use the Web Reporting GUI.

**Correct Answers: A**

2: Which command checks the Data Protector services, the media management database consistency, and that there is at least one backup of the Data Protector database?

- A. omnichck
- B. omnihealth
- C. omnidbck
- D. omnihealthck

**Correct Answers: D**

3: Between which instances is data moved during a disk staging object copy process?

- A. Media Agent and Disk Agent
- B. Media Agent and Media Agent
- C. Backup Session Manager and Disk Agent
- D. Backup Session Manager and Media Agent

**Correct Answers: B**

4: You are not able to configure a changer device on a remote media agent with the Data Protector SSE (Single Server Edition). What can you do to resolve this problem?

- A. Configure host access to the LUN.
- B. Install the required device driver for the library.
- C. Disable the RSM service on the agent system.
- D. Upgrade Data Protector to support remote devices.

**Correct Answers: D**

5: What communication technique is used for disk agent to media agent data transfer if the agents do NOT reside on the same host?

- A. RMI over LAN
- B. remote agents
- C. stream sockets
- D. pipe mechanisms

**Correct Answers: C**

6: What are the three key qualifiers Data Protector uses to identify file system objects in the database? (Select three.)

- A. device
- B. filenames

- C.hostname
- D.mountpoint
- E.description
- F.rawdisk sections

**Correct Answers: C D E**

7: What is a media pool?

- A.a collection of media of the same age
- B.a logical collection of media that belong together
- C.a concept that enables faster backup and restore
- D.a physical collection of media that is used by the same device

**Correct Answers: B**

8: How can you prevent multiple hosts from simultaneously attempting to utilize a device in one Data Protector cell?

- A.logical lock
- B.device lock
- C.lock names
- D.physical lock

**Correct Answers: C**

9: What is the maximum recommended size of a file depot for Windows?

- A.50GB
- B.100GB
- C.200GB
- D.600GB

**Correct Answers: A**

10: Which Data Protector feature simplifies shared access of several hosts to a physical device?

- A.redundant paths
- B.multipath devices
- C.device locking mechanism
- D.multiple device connections

**Correct Answers: B**

11: The Data Protector Backup Session Manager (BSM) runs on which system or systems in the cell?

- A.client only
- B.cell manager only
- C.client and cell manager
- D.dedicated installation server

**Correct Answers: B**

12: Which Data Protector process controls an active backup session?

- A.the DA (disk agent) on the Cell Client
- B.the MA (media agent) on the Cell Client
- C.the CRS (cell request server) on the Cell Manager
- D.the BSM (backup session manager) on the Cell Manager

**Correct Answers: D**

13: By default, which file is the Data Protector Database recovery file?

- A.obdb.dat
- B.obrindex.dat
- C.obdatafiles.dat
- D.obdbrecovery.dat

**Correct Answers: B**

14: Which media agent program can be used for interactively sending SCSI commands to a tape library?

- A.lma
- B.bma
- C.uma
- D.cma
- E.mma

**Correct Answers: C**

15: A tape library with two drives is connected to two hosts (host A and host B) using SCSI. Each host is accessing one drive through a dedicated SCSI connection. Host B also has access to the robotics interface. Which statement is true in this configuration?

- A.This configuration is not possible in a SCSI environment because all hosts need physical access to the robotics controller.
- B.Host A will need the media agent to control the robotics and perform all library operations for the local drive.
- C.Host B will need the media agent to control the robotics and perform all library operations.
- D.Both hosts A and B will require a "direct library" configuration to allow shared network control of the robotics.

**Correct Answers: C**